

Concurrent Reactive Plans Anticipating And Forestalling Execution Failures

Concurrent Reactive Plans Anticipating And Forestalling Execution Failures *FREE* *concurrent reactive plans anticipating and forestalling execution failures* In this book, the author presents a new computational model of forestalling common flaws in autonomous robot behavior. To this end, robots are equipped with structured reactive plans (SRPs) which are concurrent control programs that can not only be interpreted but also be reasoned about and manipulated.

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CONCURRENT REACTIVE PLANS ANTICIPATING AND FORESTALLING EXECUTION FAILURES

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